

Asymptotic properties of estimators for partially observed dependent spatial processes in a random environment.

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Breeding Bird Surveys



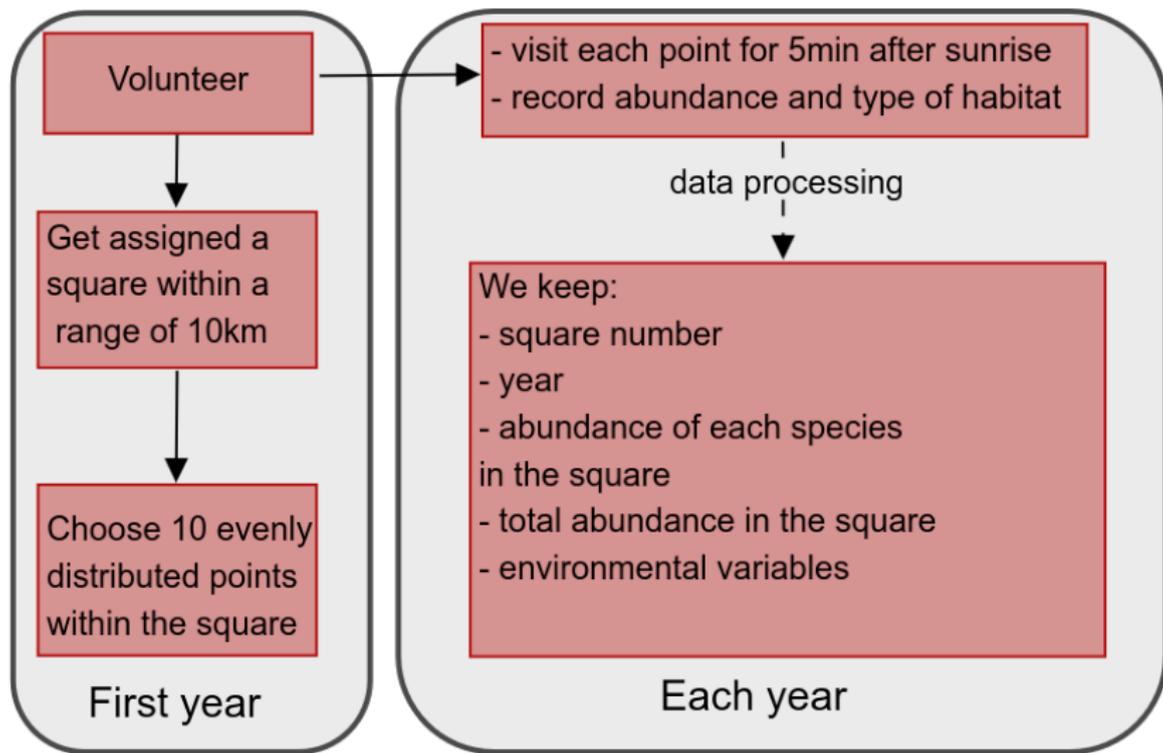
Meadow pipit (*Anthus pratensis*)

From Charles J. Sharp

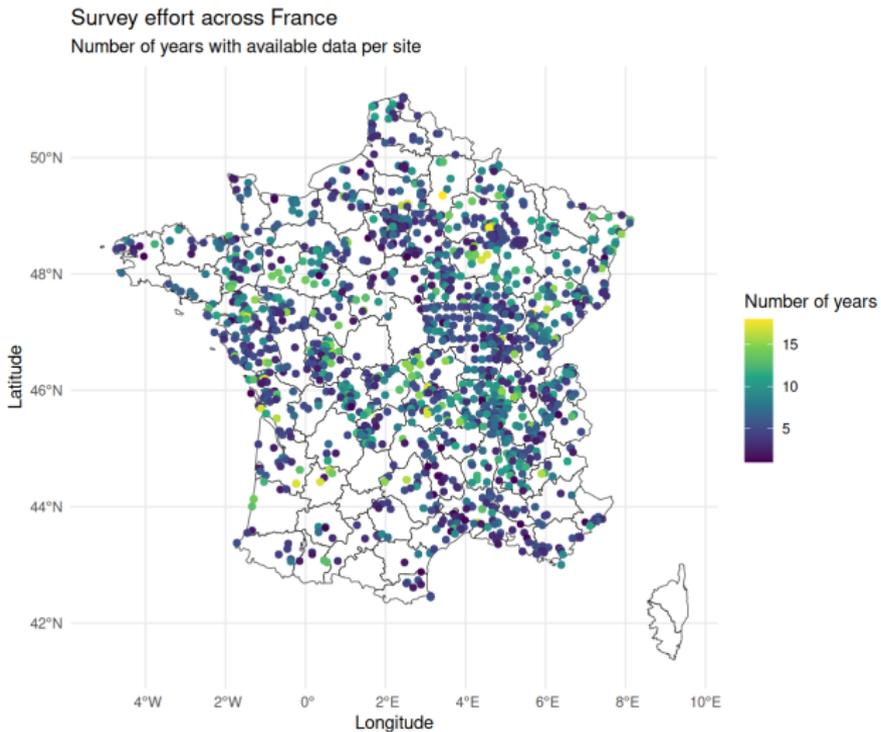
Breeding Bird Surveys (BBS) are long-term, large-scale, international avian monitoring programs designed to track the status and trends of bird populations.

Key features: standardized protocol, geographical and temporal coverage.

French BBS program (STOC)



What's in the data?



Environmental variables

For each observed point, we retrieve:

- Climate variables during spring (minimum and maximum temperature, total rain);
- Land uses in the square (% of agricultural, forest and urban land);
- Indices on how the agricultural land is fragmented 10km around the observation.

Goals

1. Give a method to estimate the variation of abundance (or future abundance) at a local scale.
2. Find which environmental variables induce changes in abundance.

Birth and death model

Individuals at a time are represented as a point process \mathcal{P} :

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The transition to a new state \mathcal{P}' is governed, by:

- birth probability: $b(\tau_x \theta, \tau_x \mathcal{P})$
- death probability: $d(\tau_x \theta, \tau_x \mathcal{P})$

with τ_x a shift operator.

Effort rate

The observers form a random set in \mathbb{R}^2 , $E = (E(x), x \in \mathbb{R}^2)$, that is independent of \mathcal{P} and θ .

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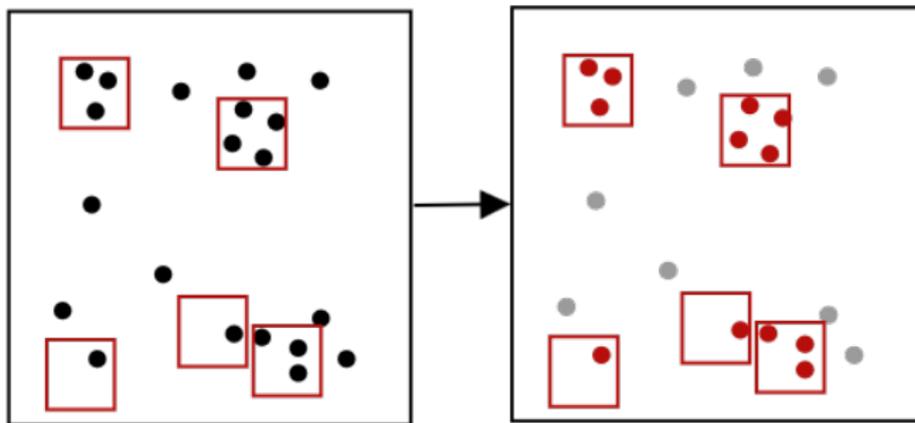
Example

$E_0 = \bigcup_e B(e, \rho)$ initial observed zone with e the location of the observers and ρ the (random) range of observation

To go to the next state of observed zone:

- each point is removed with constant rate;
- new points arrive according to a homogeneous Poisson process

Representation of the model



- birth and death process

□ observed zones

- observed individuals
- non observed individuals

(Non) stationarity assumptions

- No temporal stationarity nor equilibrium
- Not in an high density limit
- We assume our process to be spatially homogeneous

What do we want to predict?

Given a population \mathcal{P}_0 and covariates $\theta = (\theta(x), x \in \mathbb{R}^2)$.

What will be the new state \mathcal{P}_1 of the population around a point x at the next observation time?

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What will be the new state \mathcal{P}_1 of the population around a point x at the next observation time?

Two possible observables:

- Next year abundance around x : $N_1(x) = \#\{\mathcal{P}_1 \cap B(x, \rho)\}$
- Variation of abundance between the two states at x :
 $\Delta(x) = N_1(x) - N_0(x)$

Construction of \hat{N}

Let (θ', \mathcal{C}) be a deterministic configuration of interest - somewhere where we have data at the initial state and want the abundance at the next state.

How do we construct our estimator?

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How do we construct our estimator?

1. Construct a similarity function to compare two contexts.
2. Calculate similarity between (θ', \mathcal{C}) and known contexts (from the data).
3. Do a weighted mean to have an estimation of next year abundance (or variation of abundance).

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$$F_{(\theta', \mathcal{C})}(\theta, \mathcal{P}_0) = \sum_{x_i \in E} N_1(x_i) k(\tau_{x_i}(\theta, \mathcal{P}_0), (\theta', \mathcal{C}))$$

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$$Z(\theta, \mathcal{P}_0) = \sum_{x_j \in E} k(\tau_{x_j}(\theta, \mathcal{P}_0), (\theta', \mathcal{C})).$$

Estimator

Let (θ', \mathcal{C}) be a deterministic configuration of interest.

$$\begin{aligned}\hat{N}_n^{(\theta', \mathcal{C})} &:= \frac{F_{(\theta', \mathcal{C})}(\theta, \mathcal{P}_n)}{Z(\theta, \mathcal{P}_n)} \\ &= \frac{1}{\sum_{x_j \in E} k(\tau_{x_j}(\theta, \mathcal{P}_n), (\theta', \mathcal{C}))} \sum_{x_i \in E} N_1(x_i) k(\tau_{x_i}(\theta, \mathcal{P}_n), (\theta', \mathcal{C}))\end{aligned}$$

where $\mathcal{P}_n := \mathcal{P} \cap [-n/2, n/2]^2$

What we want to show

Proposition

Under some conditions:

1. *on the process \mathcal{P} ;*
2. *on the covariate field θ ;*
3. *on the similarity function k .*

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Proposition

Under some conditions:

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We have:

$$\left(\text{Var}\left(\hat{N}_n^{(\theta', \mathcal{C})}\right)\right)^{-1/2} \left(\hat{N}_n^{(\theta', \mathcal{C})} - \mathbb{E}[\hat{N}_n^{(\theta', \mathcal{C})}]\right) \xrightarrow{d} \mathcal{N}(0, 1).$$

Hypothesis on the process

Definition

The p-th order correlation function of \mathcal{P} are defined as follows:

$$\mathbb{E}\left[\prod_{i=1}^p \mathcal{P}(B_i)\right] = \int_{B_1 \times \dots \times B_p} \rho^{(p)}(x_1, \dots, x_p) dx_1 \dots dx_p$$

Hypothesis on the process

Definition (BYY26+)

\mathcal{P} has exponentially fast mixing correlation if for all $p, q \in \mathbb{N}$ and all $(x_1, \dots, x_{p+q}) \in (\mathbb{R}^2)^{p+q}$,

$$|\rho^{(p+q)}(x_1, \dots, x_{p+q}) - \rho^{(p)}(x_1, \dots, x_p)\rho^{(q)}(x_{p+1}, \dots, x_{p+q})| \leq C_{p+q}\phi(s)$$

where ϕ is a fast correlation decay function verifying:

$$-\infty \leq \liminf_{r \rightarrow \infty} \frac{\log \phi(r)}{r^b} < 0, \quad 0 < b$$

A class of admissible process

Proposition

Let Ψ be a Cox process with intensity Λ . We suppose that Λ has a (random) density with respect to the Lebesgue measure:

$$\Lambda(B) = \int_B \lambda(x) dx.$$

The p -th correlation function of Ψ is given by:

$$\rho^{(p)}(x_1, \dots, x_p) = \mathbb{E}\left[\prod_{i=1}^p \lambda(x_i)\right]$$

If $\{\lambda(x)\}_{x \in \mathbb{R}^d}$ has fast decay of correlation then Ψ has fast decay of correlation.

Log Gaussian Cox processes

Definition

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Proposition

If G is a stationary Gaussian random field and has fast decay of correlation, then the LGCP defined above verifies mixing property.

Hypothesis on the covariate field

Let θ_x be the value of the covariate field at a point $x \in \mathcal{P}$.

Definition (BYY26+)

$(\theta_x)_{x \in \mathcal{P}}$ has exponentially fast mixing correlation if for all $p, q \in \mathbb{N}$ and all $(\theta_{x,1}, \dots, \theta_{x,p+q}) \in (\mathbb{R}^2)^{p+q}$,

$$\begin{aligned} & |\mathbb{E}[f(\theta_{x,1}, \dots, \theta_{x,p})g(\theta_{x,p+1}, \dots, \theta_{x,p+q})] \\ & \quad - \mathbb{E}[f(\theta_{x,1}, \dots, \theta_{x,p})]\mathbb{E}[g(\theta_{x,p+1}, \dots, \theta_{x,p+q})]| \leq C_{p+q}\phi(s) \end{aligned}$$

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Stabilization hypothesis

Consider the marked process $\bar{\mathcal{P}} = \sum_{x \in \mathcal{P}} \delta_{(x, \theta_x)}$ and the score function $\xi : (x, \theta_x, \bar{\mathcal{P}}) \mapsto \mathbb{R}$.

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Definition (BYY19)

The radius of stabilization, $R_x^{\bar{\mathcal{P}}}$, of ξ at x and on the marked process $\bar{\mathcal{P}}$ is defined as the smallest r such that:

$$\xi(x, \theta_x, \bar{\mathcal{P}} \cap B(x, r)) = \xi(x, \theta_x, (\bar{\mathcal{P}} \cap B(x, r)) \cup (\mathcal{A} \cap B^c(x, r))),$$

with $\mathcal{A} \subset \mathbb{R}^2$.

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with $\mathcal{A} \subset \mathbb{R}^2$. ξ is said fast to be stabilizing on $\bar{\mathcal{P}}$ if for all $l \in \mathbb{N}$ there exists a fast decaying function ϕ such that:

$$\sup_{1 \leq n \leq \infty} \sup_{x_1, \dots, x_l \in [-n/2, n/2]^2} \mathbb{P}_{x_1, \dots, x_l} (R_x^{\bar{\mathcal{P}}} > t) \leq C\phi(t)$$

Admissible similarity function

Recall that we want to calculate similarity between a given context (θ', \mathcal{C}) and a context around an observed point x with:

$$\xi(x, \theta_x, \overline{\mathcal{P}}) = k(\tau_x(\theta, \mathcal{P}), \theta', \mathcal{C})$$

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Easy case: we compare (θ', \mathcal{C}) with $\overline{\mathcal{P}} \cap B(x, \rho)$ with ρ a finite range of observation.

A more challenging case: we compare (θ', \mathcal{C}) with the n closest neighbor of x .

A useful CLT

Theorem (5.2 of BYY26+)

Let $\bar{\mathcal{P}}$ be a marked point process of $\bar{\mathcal{N}}$ having exponential mixing correlations. Let $\xi : \mathbb{R}^d \times \mathcal{M} \times \bar{\mathcal{N}} \rightarrow \mathbb{R}$ be a score function that is:

- fast BL-localizing on finite windows of $\bar{\mathcal{P}}$;
- verifying the p moment condition on finite windows of $\bar{\mathcal{P}}$ for all $p \geq 1$.

If $\text{Var}(\mu_n^\xi) = \Omega(n^\nu)$ for $\nu > 0$. Then, as $n \rightarrow \infty$:

$$\left(\text{Var}(\mu_n^\xi)\right)^{-1/2} \left(\mu_n^\xi - \mathbb{E}[\mu_n^\xi]\right) \xrightarrow{d} \mathcal{N}(0, 1)$$

with $\mu_n^\xi = \sum_{x \in \mathcal{P}_n} \xi((x, U_x), \bar{\mathcal{P}})$

In our case

If \mathcal{P} has exponential mixing correlations and k verifies the stabilization hypothesis we have:

Lemma

$$(\text{Var}(F_{(\theta', \mathcal{C})}(\theta, \mathcal{P}_n)))^{-1/2} (F_{(\theta', \mathcal{C})}(\theta, \mathcal{P}_n) - \mathbb{E}[F_{(\theta', \mathcal{C})}(\theta, \mathcal{P}_n)]) \xrightarrow{d} \mathcal{N}(0, 1)$$

$$(\text{Var}(Z(\theta, \mathcal{P}_n)))^{-1/2} (Z(\theta, \mathcal{P}_n) - \mathbb{E}[Z(\theta, \mathcal{P}_n)]) \xrightarrow{d} \mathcal{N}(0, 1)$$

What about the convergence of the ratio?

In [BYY26+] they also have a LLN under the same kind of conditions.

Using Slutsky's lemma and the continuous mapping theorem we should have the convergence of the ratio and thus the following proposition:

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Using Slutsky's lemma and the continuous mapping theorem we should have the convergence of the ratio and thus the following proposition:

Proposition

$$\left(\text{Var} \left(\hat{N}_n^{(\theta', \mathcal{C})} \right) \right)^{-1/2} \left(\hat{N}_n^{(\theta', \mathcal{C})} - \mathbb{E}[\hat{N}_n^{(\theta', \mathcal{C})}] \right) \xrightarrow{d} \mathcal{N}(0, 1)$$

How does it work with a toy data set ?

Square	Year	Abundance	Environmental variables	Abundance next year
10295	2003	5		2
11158	2006	1		4
20204	2015	6		7
30363	2019	8		9
950294	2024	3		?

In our example we say that the similarity only depend on the number of geese and the habitat:

$$k(L_1, L_2) = \frac{1}{2} (\mathbb{1}_{\text{number of geese of } L_1 = \text{number of geese of } L_2} + \mathbb{1}_{\text{same habitat}})$$

Similarity matrix

Square	Year	Abundance	Environmental variables	Abundance next year	Similarity with square of interest
10295	2003	5		2	1
11158	2006	1		4	0.5
20204	2015	6		7	0
30363	2019	8		9	0.5
950294	2024	3		?	1

$$\hat{N} = \frac{2 \times 1 + 4 \times 0.5 + 7 \times 0 + 9 \times 0.5}{1 + 0.5 + 0 + 0.5 + 1}$$
$$= 2.125$$

Gower's distance function

Let L_1, L_2 be two lines in the data set. Suppose we have p variables of interest. The Gower distance is defined as:

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$$g(L_1, L_2) := \frac{1}{p} \sum_{i=1}^p d_i(L_1, L_2),$$

$$d_i(L_1, L_2) := \frac{|(L_1)_i - (L_2)_i|}{R_i} \text{ for quantitative variables,}$$

$$d_i(L_1, L_2) := \mathbb{1}_{(L_1)_i \neq (L_2)_i} \text{ for categorical variables,}$$

where R_i is the span of the i -th covariate.

$$k(L_1, L_2) = \mathbb{1}_{g(L_1, L_2) \leq \alpha},$$

$$0 \leq \alpha \leq 1$$

What happen with the Gower similarity function?

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From the table above:

$$\begin{aligned}
 g(L_1, L_5) &= \frac{1}{6} \left(\frac{|5 - 3|}{7} + \frac{|2 - 0|}{2} + \frac{|2 - 2|}{2} + \frac{|0 - 1|}{3} + 0 + 0 + 1 \right) \\
 &= \frac{55}{126} \approx 0.44
 \end{aligned}$$

What with real data?

1. Divide into train and test datasets
2. Similarity calculations:

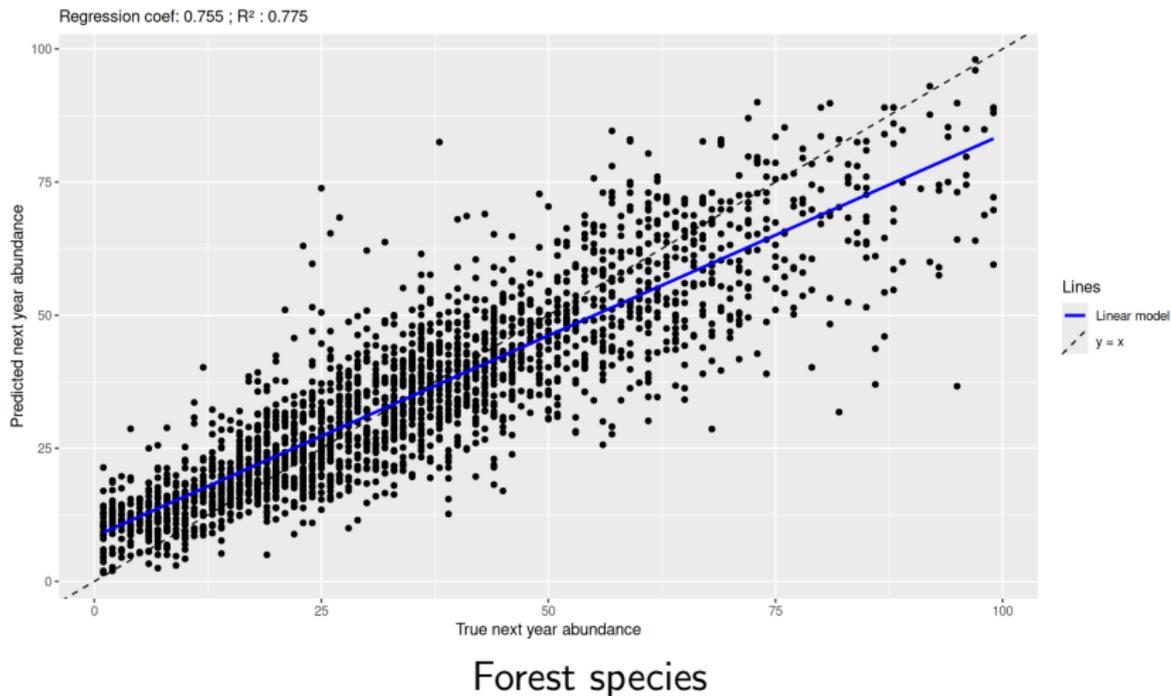
$$k(L_i, L_j) = \mathbb{1}_{g(L_1, L_2) \leq 0.05}$$

with L_i in the train set and L_j i the test set

3. Apply estimator for each line in the test set :

$$\hat{N}^{L_j} = \frac{1}{\sum_{L_i} k(L_i, L_j)} \sum_{L_i} N(L_i) k(L_i, L_j)$$

Results with real data



What's next?

- Show the mixing property for other kind of processes (Gibbs, Hawkes, ...)
- Simulations
- Try other similarity functions
- Add new environmental variables



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From Charles J. Sharp.

Thank you !



Błaszczyszyn, B., D. Yogeshwaran, and J. E. Yukich (2019). “Limit Theory for Geometric Statistics of Point Processes Having Fast Decay of Correlations”. In: *The Annals of Probability* 47.2. Publisher: Institute of Mathematical Statistics, pp. 835–895. ISSN: 0091-1798. URL: <http://www.jstor.org/stable/26613430> (visited on 10/31/2023).



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